Localized waves in FitzHugh-Nagumo equations

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Joint work with

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Pattern formation became an active research field in recent years. Reaction-diffusion systems serve as relevant models for studying complex patterns in several fields of sciences.

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Pattern formation became an active research field in recent years. Reaction-diffusion systems serve as relevant models for studying complex patterns in several fields of sciences.

A. M. Turing, Phil. Trans. R. Soc. Lond. 1952 The chemical basis of morphogenesis.

A fascinating idea proposed by Turing demonstrated that in a homogeneous medium, spatially heterogeneous distributed patterns can be produced from chemical reaction of two substances with different diffusivities.

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- Besides these regular patterns found in a neighborhood of bifurcation induced by Turing's instability, localized structures such as fronts and pulses are also observed in experiment and numerical simulation.
- Pulses are self-organized patterns with profiles that are in close proximity to a trivial background state except for one or several localized spatial regions where changes are substantial.
- Localized structures represent states which are far away from the homogeneous equilibrium.

Particle-like structures are commonly observed in physical, chemical and biological systems.



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Depending on the system parameters and initial conditions, localized dissipative structures may stay at rest or propagate with a dynamically stabilized velocity. (Localized waves)



A well-known reaction-diffusion model for studying diffusion -induced instability and emergence of patterns is the system of FitzHugh-Nagumo equations:

$$u_t - \Delta u = \frac{1}{d}(f(u) - v) \qquad u: \text{ activator}$$

$$v_t - \Delta v = u - \gamma v \qquad v: \text{ inhibitor}$$

$$\gamma > 0 \qquad f: \text{ cubic polynomial}$$
(FN)

Suppose (u(x - ct), v(x - ct)) satisfies (FN), then when viewed by someone moving with the speed c, this solution keeps the same profile. Such a solution is referred to as a traveling wave, while it is a stationary pattern or standing wave if c = 0. We may consider the case c > 0 only; for otherwise, reverse the direction of wave motion will do. Recall that

$$u_t = u_{xx} + f(u) - v$$
$$v_t = \varepsilon(u - \gamma v)$$

is a simplified model for the Hodgkin-Huxley system to describe the electrical impulses in the axon of the squid. Here (u, v) = (0, 0) is the rest state, and the nerve impulse is generated by a finite excitation; the homogeneous ground state relaxes the characteristic shape of the pulse. For $\varepsilon \ll 1$, the existence of a traveling pulse has been treated as a singular perturbation problem in which the pulse is constructed by stitching together solutions of certain reduced systems. ・ロト ・ 同ト ・ ヨト ・ ヨト ・ りゃぐ For the nullclines in the (u, v) plane, if $\gamma < 4/(1 - \beta)^2$ the straight line $v = u/\gamma$ intersects the curve v = f(u) at one point (0, 0) only.

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Theorem. Let $\beta \in (0, 1/2)$ be given.

- (i) There exist $\hat{\gamma} > 0$ and $\hat{d} = \hat{d}(\gamma) > 0$ such that if $\gamma < \hat{\gamma}$ and $d < \hat{d}$, then there is a standing pulse solution (u, v) of (FN).
- (ii) Both u and v are even functions on $(-\infty, \infty)$ and satisfy $(u, v) \to (0, 0)$ as $x \to \infty$.
- (iii) u changes signs exactly once in $(0, \infty)$ while v > 0 and v' < 0 on $(0, \infty)$.

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The profile of a standing pulse



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The profile of a traveling pulse



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There have been many interesting works on the traveling wave solutions for scalar reaction-diffusion equation

$$u_t = \Delta u + f(u).$$

A planar traveling wave satisfies an ordinary differential equation; the existence question has been studied by various methods. Lucia, Muratov and Novaga considered the functional

$$I_c[u] = \int_{\mathbf{R}} (\frac{1}{2}u_x^2 + F(u))e^{cx}dx,$$

where $F(u) = -\int_0^u f(s)ds$. Since $I_c(w(\cdot - a)) = e^a I_c(w)$, they seek a minimizer u_c of I_c under the constraint $\int_{\mathbf{R}} u_x^2 e^{cx} dx = 1$. When $I_c[u_c] \leq 0$, letting $\hat{c} = c\sqrt{1 - I_c[u_c]}$ and $\hat{u}(x) = u_c(\hat{c}x/c)$, they showed that \hat{u} is a travelling wave with speed \hat{c} .

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Heinze considered a different type of ansatz $u(c(\xi - ct), y)$ in the change of variables. Then a function satisfying

$$c^2(u_{xx} + u_x) + \Delta_y u + f(u) = 0$$

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represents a traveling wave solution.

Let **H** denote the Hilbert space equipped with the norm $||u||_{\mathbf{H}} = \int_{\Omega} (u_x^2 + |\nabla_y u|^2 + u^2) e^x dx dy$, where Ω is a cylinder. Heinze viewed a traveling wave solution \hat{u} as a minimizer of $\int_{\Omega} \frac{1}{2} u_x^2 e^x dx dy$ subject to the constraint $\{u \in \mathbf{H} : \int_{\Omega} [\frac{1}{2} |\nabla_y u|^2 + F(u)] e^x dx dy = -1\}$. A stimulating result of this approach is that the Lagrange multiplier is nothing but $\frac{1}{c^2}$, where |c| gives the wave speed. Following the ansatz proposed by Heinze, we study the homoclinic solutions of

$$\begin{cases} dc^{2}u_{xx} + dc^{2}u_{x} + f(u) - v = 0, \\ c^{2}v_{xx} + c^{2}v_{x} + u - \gamma v = 0. \end{cases}$$
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Indeed if (u, v) satisfies (1) for some c > 0, there is a traveling wave to (FN). In particular, if $(u, v) \to (0, 0)$ as $|x| \to \infty$ then this is a traveling pulse solution.

Let $L_{ex}^2 = \{u : \int_{-\infty}^{\infty} e^x (u(x))^2 dx < \infty\}$ be a Hilbert space equipped with a weighted norm $||u||_{L_{ex}^2} \equiv \sqrt{\int_{-\infty}^{\infty} e^x u^2 dx}$. The Green function G of the differential operator $(\gamma - c^2 \frac{d^2}{dx^2} - c^2 \frac{d}{dx})$ is a positive function given by $\int \frac{1}{c\sqrt{c^2 + 4\gamma}} e^{-r_2 s} e^{r_2 x}$, if x < s,

$$G(x,s) = \begin{cases} c\sqrt{c^2+4\gamma} & f(x,s) \\ \frac{1}{c\sqrt{c^2+4\gamma}}e^{-r_1s} e^{r_1x}, & \text{if } x > s. \end{cases}$$

Here the solutions of the characteristic equation

 $c^2r^2 + c^2r - \gamma = 0$ are $\frac{1}{2c}(-c \pm \sqrt{c^2 + 4\gamma})$, denoted by r_1 and r_2 with $r_1 < -1 < 0 < r_2$.

 $\mathcal{L}_c: L^2_{ex} \to L^2_{ex}$, since $1 + 2r_1 < 0$ and $1 + 2r_2 > 0$.

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$$\int_{\mathbf{R}} e^{x} u_{1}(x) \mathcal{L}_{c} u_{2}(x) dx = \int_{\mathbf{R}} \int_{\mathbf{R}} e^{x} e^{s} g(x,s) u_{1}(x) u_{2}(s) ds dx$$
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that is, $\mathcal{L}_c: L^2_{ex} \to L^2_{ex}$ is self-adjoint.

$$\mathcal{L}_{c}u(x) = \frac{e^{r_{1}x}}{c\sqrt{c^{2}+4\gamma}} \int_{-\infty}^{x} e^{-r_{1}s} u(s) \, ds + \frac{e^{r_{2}x}}{c\sqrt{c^{2}+4\gamma}} \int_{x}^{\infty} e^{-r_{2}s} u(s) \, ds$$

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Define $F(\xi) = -\int_0^{\xi} f(\eta) \, d\eta = \xi^4/4 - (1+\beta)\xi^3/3 + \beta\xi^2/2$. Let H_{ex}^1 be a Hilbert space equipped with the norm

$$||w||_{H^1_{ex}} = \sqrt{\int_{\mathbf{R}} e^x w_x^2 \, dx} + \int_{\mathbf{R}} e^x w^2 \, dx$$

Consider a functional $J_c: H^1_{ex} \to \mathbf{R}$ defined by

$$J_c(w) \equiv \int_{\mathbf{R}} e^x \left\{ \frac{dc^2}{2} w_x^2 + \frac{1}{2} w \mathcal{L}_c w + F(w) \right\} dx .$$

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• If $a \in \mathbf{R}$ and $w \in L^2_{ex}$ then $\mathcal{L}_c(w(\cdot - a)) = (\mathcal{L}_c w)(\cdot - a)$.

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$$J_c(w) \equiv \int_{\mathbf{R}} e^x \{ \frac{dc^2}{2} w_x^2 + \frac{1}{2} w \mathcal{L}_c w + F(w) \} dx .$$

• If $a \in \mathbf{R}$ and $w \in L^2_{ex}$ then $\mathcal{L}_c(w(\cdot - a)) = (\mathcal{L}_c w)(\cdot - a)$.

• For any $a \in \mathbf{R}$ and $w \in H^1_{ex}$, $J_c(w(\cdot - a)) = e^a J_c(w)$.

If
$$w \in H^1_{ex}(\mathbf{R})$$
 then
$$\begin{cases} \frac{1}{4} \int_{\mathbf{R}} e^x w^2 \, dx &\leq \int_{\mathbf{R}} e^x w_x^2 \, dx ,\\ e^x w^2(x) &\leq \int_x^\infty e^y w_y^2 \, dy . \end{cases}$$

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• $\mathcal{L}_c(L^2_{ex}) \subset H^1_{ex}$. In fact

$$\|\mathcal{L}_{c}u\|_{H^{1}_{ex}} \leq \frac{2\sqrt{5}}{c^{2}} \|u\|_{L^{2}_{ex}}.$$

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$$\begin{cases} \frac{1}{4} \int_{\mathbf{R}} e^x w^2 \, dx &\leq \int_{\mathbf{R}} e^x w_x^2 \, dx ,\\ e^x w^2(x) &\leq \int_x^\infty e^y w_y^2 \, dy . \end{cases}$$

• $\mathcal{L}_c(L_{ex}^2) \subset H_{ex}^1$. In fact

$$\|\mathcal{L}_{c}u\|_{H^{1}_{ex}} \leq \frac{2\sqrt{5}}{c^{2}}\|u\|_{L^{2}_{ex}}$$

• For any $w \in H^1_{ex}$, $\int_{\mathbf{R}} e^x w_x^2 dx \le \|w\|_{H^1_{ex}}^2 \le 5 \int_{\mathbf{R}} e^{cx} w_x^2 dx;$

in other words, $||w_x||_{L^2_{ex}}$ is an equivalent norm for H^1_{ex} .

$$\begin{cases} \|v\|_{L^{2}_{ex}} \leq \frac{4}{c^{2}} \|u\|_{L^{2}_{ex}} ,\\ \|v'\|_{L^{2}_{ex}} \leq \frac{2}{c^{2}} \|u\|_{L^{2}_{ex}} ,\\ 0 \leq \int_{\mathbf{R}} e^{x} \{c^{2} (\mathcal{L}_{c} u)'^{2} + \gamma (\mathcal{L}_{c} u)^{2} \} \, dx = \int_{\mathbf{R}} e^{x} u \, \mathcal{L}_{c} u \, dx . \end{cases}$$

Let

$$\mathcal{A} \equiv \{ w \in H^1_{ex} : \int_{\mathbf{R}} e^x w_x^2 \, dx = 2. \}.$$

To seek traveling pulse solutions, we begin with studying the functional $J_c : \mathcal{A} \to \mathbf{R}$. Set $\mathcal{J}(c) \equiv \inf_{w \in \mathcal{A}} J_c(w)$.

Lemma. There exists a $\bar{c} = \bar{c}(d,\beta) > 0$ such that if $c \ge \bar{c}$ then $\mathcal{J}(c) > 0$.

Proof. For $w \in \mathcal{A}$, since the nonlocal term is non-negative,

$$J_{c}(w) \geq \frac{dc^{2}}{2} \int_{\mathbf{R}} e^{x} w_{x}^{2} dx + \int_{\mathbf{R}} e^{x} F(w) dx$$

$$\geq dc^{2} - M_{2} \int_{\mathbf{R}} e^{x} w^{2} dx$$

$$\geq dc^{2} - 8M_{2}$$

$$\geq 8M_{2}.$$

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Clearly $\mathcal{J}(c) > 0$ if $\bar{c} = 4\sqrt{M_2/d}$.

The next step is to show that $\mathcal{J}(c) < 0$ when c is small. Let y = x/c and $\tilde{\mathcal{L}}_c = (\gamma - \frac{d^2}{dy^2} - c\frac{d}{dy})^{-1}$. For $u \in \mathcal{A}$, if $\tilde{u}(y) \equiv u(x)$, it is easy to check that $\tilde{\mathcal{L}}_c \tilde{u}(y) = \mathcal{L}_c u(x)$, so is $\tilde{v}(y) = \tilde{\mathcal{L}}_c \tilde{u}(y)$ Clearly $u \in H_{ex}^1$ if and only if $\tilde{u} \in H_c^1(\mathbf{R}) = \{w : \int_{\mathbf{R}} e^{cy} w_y^2 dy < \infty\}$. Similarly $\mathcal{L}_c u \in H_{ex}^1$ if and only if $\tilde{\mathcal{L}}_c \tilde{u} \in H_c^1$. A direct calculation gives

$$J_{c}(u) = \int_{\mathbf{R}} e^{x} \{ \frac{dc^{2}}{2} (u'(x))^{2} + F(u(x)) + \frac{1}{2} u(x) \mathcal{L}_{c} u(x) \} dx = c \int_{\mathbf{R}} e^{cy} \{ \frac{d}{2} (\tilde{u}'(y))^{2} + F(\tilde{u}(y)) + \frac{1}{2} \tilde{u}(y) \tilde{\mathcal{L}}_{c} \tilde{u}(y) \} dy .$$

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Consider a piecewise linear function defined by

$$q_0(y) \equiv \begin{cases} 1, & \text{if } 0 \le y \le a, \\ \frac{(b-y)}{b-a}, & \text{if } a \le y \le b, \\ 0, & \text{if } y \ge b. \end{cases}$$

With an even extension, q_0 has a compact support on the real line. It has been shown that there is a $k_1 > 0$ such that

$$\int_{\mathbf{R}} \{ \frac{d}{2} q_0'^2 + F(q_0) + \frac{1}{2} q_0 \, \tilde{\mathcal{L}}_0 q_0 \, \} \, dy < 0$$

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if $d \leq k_1 \gamma$.

Lemma. Let $c \ge 0$ and $\{c_n\}_{n=1}^{\infty} \subset [0,\infty)$ such that $|c_n - c| \le \min\{1,\gamma\}$ and $c_n \to c$ if $n \to \infty$. Suppose that there exists a $\delta > 0$ such that $(c - \delta)^+ \le c_n \le c + \delta$. If $w \in H_s^1$ for all $(c - \delta)^+ \le s \le c + \delta$, then $\|\tilde{\mathcal{L}}_{c_n}w - \tilde{\mathcal{L}}_c w\|_{H_c^1} \le \frac{2(1+\gamma)}{\gamma^2} |c_n - c| \|w\|_{L_c^2}$.

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Lemma. Let $c \ge 0$ and $\{c_n\}_{n=1}^{\infty} \subset [0,\infty)$ such that $|c_n - c| \le \min\{1,\gamma\}$ and $c_n \to c$ if $n \to \infty$. Suppose that there exists a $\delta > 0$ such that $(c - \delta)^+ \le c_n \le c + \delta$. If $w \in H_s^1$ for all $(c - \delta)^+ \le s \le c + \delta$, then $\|\tilde{\mathcal{L}}_{c_n}w - \tilde{\mathcal{L}}_c w\|_{H_c^1} \le \frac{2(1 + \gamma)}{\gamma^2} |c_n - c| \|w\|_{L_c^2}$. Lemma. If $d \le d_0$ then $\mathcal{J}(c) < 0$ for $c \in (0, \underline{c})$.

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Lemma. Let $c \geq 0$ and $\{c_n\}_{n=1}^{\infty} \subset [0,\infty)$ such that $|c_n - c| \leq \min\{1, \gamma\}$ and $c_n \to c$ if $n \to \infty$. Suppose that there exists a $\delta > 0$ such that $(c - \delta)^+ \leq c_n \leq c + \delta$. If $w \in H^1_{\circ}$ for all $(c-\delta)^+ < s < c+\delta$, then $\|\tilde{\mathcal{L}}_{c_n} w - \tilde{\mathcal{L}}_c w\|_{H^1_c} \le \frac{2(1+\gamma)}{\gamma^2} |c_n - c| \|w\|_{L^2_c}.$ **Lemma.** If $d \leq d_0$ then $\mathcal{J}(c) < 0$ for $c \in (0, c)$. **Lemma.** Let c > 0 and $\{c_n\}_{n=1}^{\infty} \subset (c/\sqrt{2}, c\sqrt{3}/\sqrt{2})$ such that $c_n \to c$ as $n \to \infty$. Then there exists a $M_4 > 0$ such that

$$\|\mathcal{L}_{c_n} w - \mathcal{L}_c w\|_{H^1_{ex}} \le M_4 \, |c_n^2 - c^2| \, \|w\|_{L^2_{ex}}$$

for all $w \in H^1_{ex}$. Here M_4 is continuous in γ and c, and bounded if c is bounded away from zero.

Lemma. The function $\mathcal{J} : [\underline{c}, \overline{c}] \to \mathbf{R}$ is continuous.

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Lemma. The function $\mathcal{J} : [\underline{c}, \overline{c}] \to \mathbf{R}$ is continuous. **Lemma.** There exists a $c_0 \in [\underline{c}, \overline{c}]$ such that $\mathcal{J}(c_0) = 0$.

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Lemma. The function $\mathcal{J} : [\underline{c}, \overline{c}] \to \mathbf{R}$ is continuous. **Lemma.** There exists a $c_0 \in [\underline{c}, \overline{c}]$ such that $\mathcal{J}(c_0) = 0$. **Lemma.** There is a $u_0 \in \mathcal{A}$ such that $J_{c_0}(u_0) = 0$.

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Lemma. The function $\mathcal{J} : [\underline{c}, \overline{c}] \to \mathbf{R}$ is continuous. **Lemma.** There exists a $c_0 \in [\underline{c}, \overline{c}]$ such that $\mathcal{J}(c_0) = 0$. **Lemma.** There is a $u_0 \in \mathcal{A}$ such that $J_{c_0}(u_0) = 0$. A Poincare type inequality shows that this solution decays to (0,0) at $+\infty$. However, it is more delicate and usually requires more efforts to investigate the asymptotic behavior of a traveling wave near $-\infty$ when such a solution is obtained from a weighted function space like H_{ex}^1 via a variational approach In some situations, for instance in case of scalar reaction-diffusion equations, the maximum principle provides a help to complete this task.

We minimize J_c over the set of admissible functions in the class -/+/-. Roughly speaking, this is a topological constraint which requires that the functions in the admissible set change sign at most twice.



Let $\beta < \beta_1 < 1 < \beta_2$ satisfy $F(\beta_1) = F(\beta_2) = 0$. A continuous function w is in the class -/ + /-, if there exist $-\infty \le x_1 \le x_2 \le \infty$ such that $w \le 0$ on $(-\infty, x_1] \cup [x_2, \infty)$, and $w \ge 0$ on $[x_1, x_2]$. The choice of x_1, x_2 is not necessarily unique. For instance, if $x_1 = -\infty$ and $x_2 = \infty$, then $w \ge 0$ on the real line. In case $x_1 = x_2 = \infty$, then $w \le 0$ on the real line. Both examples are included in the class -/ + /-.



The qualitative properties of the global minimizer u_0 can be accessed by arguing indirectly and performing step by step either local or global surgeries on u_0 to generate a new function $u_{new} \in \mathcal{A}$ with $J_c(u_{new}) < J_c(u_0)$.

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Lemma. Suppose that $u_{new} \in H^1_{ex}$, a function after making some changes on u_0 . Then the change in the nonlocal term is

$$\int_{\mathbf{R}} e^x(u_{new} \mathcal{L}_c u_{new} - u_0 \mathcal{L}_c u_0) = \int_{\mathbf{R}} e^x(u_{new} - u_0) \mathcal{L}_c(u_{new} + u_0) .$$

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Proof. It is a direct consequence of the fact that \mathcal{L}_c is self adjoint with respect to the L_{ex}^2 inner product.

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Proof. It is a direct consequence of the fact that \mathcal{L}_c is self adjoint with respect to the L_{ex}^2 inner product.

Remark. If the support of $u_{new} - u$ lies inside a finite interval [a, b], then the change in the nonlocal term can be calculated within the same interval [a, b]. When $u_{new} - u$ is small, $\mathcal{L}_c u_{new}$ is close to $\mathcal{L}_c u$ on [a, b], even though the decay behavior and the sign of $\mathcal{L}_c u_{new}$ near infinity can differ from those of $\mathcal{L}_c u$.

Let u_0 be a minimizer. The next lemma enables us to eliminate the possibility that a sharp corner appears on the graph of u_0 .

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Corner Lemma If x_0 and $\ell > 0$ are numbers such that $u_0(x_0) = 0$ and $u_0 \in C^1[x_0 - \ell, x_0] \cap C^1[x_0, x_0 + \ell]$, then $\lim_{x \to x_0^-} u'_0(x) = \lim_{x_0 \to x_0^+} u'_0(x)$.

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Corner Lemma If x_0 and $\ell > 0$ are numbers such that $u_0(x_0) = 0$ and $u_0 \in C^1[x_0 - \ell, x_0] \cap C^1[x_0, x_0 + \ell]$, then $\lim_{x \to x_0^-} u'_0(x) = \lim_{x_0 \to x_0^+} u'_0(x)$.

The inherited technical difficulty associated with the topological class \mathcal{A} is partly alleviated.

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The idea for the proof of corner lemma.

We argue indirectly. Suppose $u_0(x_0) = 0$, $\lim_{x \to x_0^-} u'_0(x) = a_1$ and $\lim_{x_0 \to x_0^+} u'_0(x) = a_2$ with $a_1 \neq a_2$. If u_0 were straight lines on either side of x_0 , then

$$u_0(x) = \begin{cases} a_1(x - x_0) , & \text{if } x_0 - \ell \le x \le x_0, \\ a_2(x - x_0) , & \text{if } x_0 \le x \le x_0 + \ell. \end{cases}$$

If the points $(x_0 - \ell, u_0(x_0 - \ell))$ and $(x_0 + \ell, u_0(x_0 + \ell))$ on the graph of u_0 is joined by a straight line, the slope of this line is $(a_1 + a_2)/2$. This simple example gives a basic idea in the proof.

For a general C^1 function u_0 , if $\ell_1 << \ell$, then $u'_0(x) = a_1 + o(1)$ for $x_0 - \ell_1 \le x \le x_0$; $u'_0(x) = a_2 + o(1)$ for $x_0 \le x \le x_0 + \ell_1$; and the straight line $y = L_1(x)$ joining $(x_0 - \ell_1, u_0(x_0 - \ell_1))$ and $(x_0 + \ell_1, u_0(x_0 + \ell_1))$ has a slope of $(a_1 + a_2)/2 + o(1)$. Set

$$u_{new}(x) = \begin{cases} u_0(x), & \text{if } x \le x_0 - \ell_1, \\ L_1(x), & \text{if } x_0 - \ell_1 \le x \le x_0 + \ell_1, \\ u_0(x), & \text{if } x \ge x_0 + \ell_1. \end{cases}$$

Then

$$\frac{d}{2} \int_{x_0-\ell_1}^{x_0+\ell_1} \{(u_{new})_x^2 - (u_0)_x^2\} e^x dx$$

$$= \frac{d}{2} \{\left(\frac{(a_1+a_2)}{2} + o(1)\right)^2 2\ell_1 - (a_1+o(1))^2\ell_1 - (a_2+o(1))^2\ell_1\}$$

$$= -\frac{d\ell_1}{4} \left((a_1-a_2)^2 + o(1)\right) < 0.$$

Employing the mean value theorem yields

$$\int_{x_0-\ell_1}^{x_0+\ell_1} \{F(u_{new}) - F(u_0)\} e^x dx = -\int_{x_0-\ell_1}^{x_0+\ell_1} f(\tilde{u})(u_{new}-u_0) e^x dx$$

for some \tilde{u} lying in between u_0 and u_{new} . Since

$$u_{new} - u_0 = O(\ell_1),$$

$$\left| \int_{x_0 - \ell_1}^{x_0 + \ell_1} \{ F(u_{new}) - F(u_0) \} e^x dx \right| \le \ell_1 O(\ell_1),$$

which is negligible compared with the change in the gradient term of J.

Now turn to the nonlocal term of J. Since both $|\mathcal{L}_c u_0|$ and $|\mathcal{L}_c u_{new}|$ are bounded and $|u_{new} - u_0| = O(\ell_1)$,

$$\left|\frac{1}{2}\int_{x_0-\ell_1}^{x_0+\ell_1} \{u_{new}\,\mathcal{L}_c u_{new} - u_0\,\mathcal{L}_c u_0\}\,e^x dx\,\right| \le \ell_1\,O(\ell_1)\,,$$

which is also negligible compared with the change in the gradient term.

Therefore $J(u_{new}) < J(u_0)$ with $u_{new} \in \mathcal{A}$. This contradicts u_0 being a minimizer in \mathcal{A} .

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Lemma. Let $\psi = u_0 + \alpha v_0$. Then ψ is positive everywhere,

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Theorem. Given $\beta \in (0, 1/2)$ and $\gamma < 4/(1 - \beta)^2$, there is a $\hat{d} = \hat{d}(\gamma)$ such that if $d \leq \hat{d}$ then for some c > 0, (FN) possesses a traveling pulse solution (u_0, v_0) . Moreover $u_0, v_0 \in C^{\infty}(\mathbf{R})$ and are exponentially decaying to 0 as $|x| \to \infty$.

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Suppose that $u_0 \ge 0$ and oscillates infinite number of times near $-\infty$. Then $u_0 \ge 0$ on $(-\infty, z_3]$. For $x_1 < x_2 < z_3$, $w_1(x_1, x_2) \equiv dc_0^2(u'_0(x_2) - u'_0(x_1) + u_0(x_2) - u_0(x_1))$ $= \int_{x_1}^{x_2} v_0 \, dx - \int_{x_1}^{x_2} f(u_0) \, dx$,

Then w_1 is uniformly bounded for any choice of x_1 and x_2 .

$$\gamma \int_{x_1}^{x_2} v_0 \, dx - \int_{x_1}^{x_2} u_0 \, dx = w_2(x_1, x_2) \; .$$

$$w_1 - \frac{w_2}{\gamma} = \int_{x_1}^{x_2} \{\frac{u_0}{\gamma} - f(u_0)\} \, dx \ge m \int_{x_1}^{x_2} u_0 \, dx$$

for some positive constant m, since the graph v = f(u) lies underneath the line $v = u/\gamma$ when $u \ge 0$. Thus

$$0 < \int_{-\infty}^{z_3} u_0 \, dx \le M/m \; .$$

Suppose there exist $a_1 < b_1 \le a_2 < b_2 \le a_3 < b_3 \dots$ in the interval $[x_0 - \ell, x_0]$ such that

$$\begin{cases} u_0 < \beta_2 & \text{on intervals } (a_i, b_i), \ i = 1, 2, \dots, \\ u_0 = \beta_2 & \text{on } [x_0 - \ell, x_0] \setminus \bigcup_{i=1}^{\infty} (a_i, b_i), \end{cases}$$

with both $a_i \to x_0^-$ and $b_i \to x_0^-$, then $u_0 \in C^1[x_0 - \ell, x_0)$ by Corner Lemma.